

THE ERDŐS–KO–RADO THEOREM FOR TWISTED GRASSMANN GRAPHS

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ABSTRACT. We present a “modern” approach to the Erdős–Ko–Rado theorem for Q -polynomial distance-regular graphs and apply it to the twisted Grassmann graphs discovered in 2005 by van Dam and Koolen.

1. INTRODUCTION

The 1961 theorem of Erdős, Ko and Rado [8] asserts that the largest possible families Y of d -subsets of a v -set such that $|x \cap y| \geq t$ for all $x, y \in Y$ where $v > (t+1)(d-t+1)$ are the families of all d -subsets containing some fixed t -subset. In fact, the exact bound $v > (t+1)(d-t+1)$ was obtained later by Wilson [26] as an application of Delsarte’s linear programming method [6]. It is natural to think of this theorem as a result about (vertex) subsets of the Johnson graphs $J(v, d)$, and analogous theorems are known for several other families of distance-regular graphs, e.g., Hamming graphs $H(d, q)$ ($q \geq t+2$) [19], Grassmann graphs $J_q(v, d)$ ($v \geq 2d$) [14, 10, 11, 23], bilinear forms graphs $\text{Bil}_q(d, e)$ ($d \leq e$) [15, 11, 23].

In this note, we first distill common algebraic techniques found in some of the proofs of these “Erdős–Ko–Rado theorems” into a unified approach for general Q -polynomial distance-regular graphs Γ .¹ Our approach is also “modern” in the sense that it is based on and motivated by the theory of two parameters, *width* w and *dual width* w^* , of a subset Y of Γ introduced in 2003 by Brouwer et al. [4]. In this setting, the “ t -intersecting” condition amounts to requiring $w \leq d - t$ where d is the diameter of Γ , and we shall view the Erdős–Ko–Rado theorem as characterizing those subsets Y with $w = d - t$ and $w^* = t$ by their sizes among all t -intersecting families. There are two steps involved: (1) construction of a specific feasible solution to the dual of a linear programming problem; (2) classification of the *descendents* [24] of Γ , i.e., those subsets having the property $w + w^* = d$. We demonstrate this approach by deriving the Erdős–Ko–Rado theorem for the *twisted Grassmann graphs* $\tilde{J}_q(2d+1, d)$ discovered in 2005 by van Dam and Koolen [5].

2. A “MODERN” APPROACH TO THE ERDŐS–KO–RADO THEOREM FOR Q -POLYNOMIAL DISTANCE-REGULAR GRAPHS

Let $\Gamma = (X, R)$ be a finite connected simple graph with diameter d and path-length distance ∂ , and $\mathbb{R}^{X \times X}$ the set of real matrices with rows and columns indexed by X . For each i ($0 \leq i \leq d$), let $A_i \in \mathbb{R}^{X \times X}$ be the adjacency matrix of

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¹ Q -polynomial distance-regular graphs are thought of as finite/combinatorial analogues of symmetric spaces of rank one; see [2, pp. 311–312].

the distance- i graph Γ_i of Γ , so $A_0 = I$ and $\sum_{i=0}^d A_i = J$, the all ones matrix. We say Γ is *distance-regular* if $\mathbf{A} := \text{span}\{A_0, A_1, \dots, A_d\}$ is closed under ordinary matrix multiplication; or equivalently, \mathbf{A} is a (commutative) algebra. (The reader is referred to [2, 3, 13] for background material on distance-regular graphs.) Throughout this note, suppose Γ is distance-regular. We call \mathbf{A} the *Bose–Mesner algebra* of Γ . It is semisimple (as it is closed under transposition) and therefore has a basis $\{E_i\}_{i=0}^d$ consisting of the primitive idempotents; we always set $E_0 = |X|^{-1}J$. Note that \mathbf{A} is also closed under entrywise multiplication, denoted \circ . We shall assume Γ is *Q-polynomial* with respect to the ordering $\{E_i\}_{i=0}^d$, i.e., $E_1 \circ E_i$ is a linear combination of E_{i-1}, E_i, E_{i+1} with nonzero coefficients for E_{i-1}, E_{i+1} ($0 \leq i \leq d$), where $E_{-1} = E_{d+1} = 0$. Let $Q = (Q_{ij})_{0 \leq i, j \leq d}$ be the *second eigenmatrix* of Γ :

$$E_j = \frac{1}{|X|} \sum_{i=0}^d Q_{ij} A_i \quad (0 \leq j \leq d).$$

Let Y be a nonempty subset of X and $\chi \in \mathbb{R}^X$ its (column) characteristic vector. Brouwer et al. [4] defined the *width* w and *dual width* w^* of Y as follows:

$$w = \max\{i : \chi^\top A_i \chi \neq 0\}, \quad w^* = \max\{i : \chi^\top E_i \chi \neq 0\}.$$

They showed (among other results) that

$$(1) \quad w + w^* \geq d.$$

We call Y a *descendent* [24] of Γ if $w + w^* = d$. It should be remarked that every descendent is a so-called completely regular code (cf. [17]), and that the induced subgraph is a Q -polynomial distance-regular graph provided it is connected; see [4, Theorems 1–3]. See also [24] for more information on descendents.

Now fix an integer t ($0 < t < d$) and suppose $w \leq d - t$; in other words, Y is “ t -intersecting”. We recall the inner distribution $\mathbf{e} = (e_0, e_1, \dots, e_d)$ of Y :

$$e_i = \frac{1}{|Y|} \chi^\top A_i \chi, \quad (\mathbf{e}Q)_i = \frac{|X|}{|Y|} \chi^\top E_i \chi \quad (0 \leq i \leq d).$$

It follows that $|Y| = (\mathbf{e}Q)_0$ and

$$e_0 = 1, \quad e_1 \geq 0, \dots, e_{d-t} \geq 0, \quad e_{d-t+1} = \dots = e_d = 0, \\ (\mathbf{e}Q)_1 \geq 0, \dots, (\mathbf{e}Q)_d \geq 0.$$

(Observe that the E_i are positive semidefinite.) Following [6], we view these as a linear programming maximization problem. A vector $\mathbf{f} = (f_0, f_1, \dots, f_d)$ satisfying (2), (3) below gives a feasible solution to its dual problem:

$$(2) \quad f_0 = 1, \quad f_1 = \dots = f_t = 0, \quad f_{t+1} > 0, \dots, f_d > 0,$$

$$(3) \quad (\mathbf{f}Q^\top)_1 = \dots = (\mathbf{f}Q^\top)_{d-t} = 0.$$

Indeed, we have

$$|Y| = (\mathbf{e}Q)_0 \leq \mathbf{e}Q\mathbf{f}^\top = (\mathbf{f}Q^\top)_0$$

with equality if and only if $(\mathbf{e}Q)_{t+1} = \dots = (\mathbf{e}Q)_d = 0$, i.e., $w^* \leq t$. By virtue of (1), it follows that

Lemma 1. *Let Y be a nonempty subset of X with $w \leq d - t$. Suppose there is a vector $\mathbf{f} = (f_0, f_1, \dots, f_d)$ satisfying (2), (3). Then $|Y| \leq (\mathbf{f}Q^\top)_0$, and equality holds if and only if Y is a descendent of Γ with $w = d - t$ and $w^* = t$. ■*

The vector \mathbf{f} above is of independent interest from the point of view of *Leonard systems*² [25] and will be discussed in detail in a future paper. Here we mention that \mathbf{f} can be found for the following graphs:

Γ	$(\mathbf{f}Q^\Gamma)_0$
$J(v, d) \ (v > (t+1)(d-t+1))$	$\binom{v-t}{d-t}$
$H(d, q) \ (t = d-1; \text{ or } q \geq d; \text{ or } q = d-1, t < d-2)$	q^{d-t}
$J_q(v, d) \ (v \geq 2d)$	$\begin{bmatrix} v-t \\ d-t \end{bmatrix}_q$
$\text{Bil}_q(d, e) \ (d \leq e)$	$q^{(d-t)e}$

For $\Gamma = J(v, d)$ or $J_q(v, d)$ (with v, d as in the table), Wilson and Frankl [26, 10] constructed a matrix $B \in \mathbf{A}$ such that (i) $B_{xy} = 0$ if $\partial(x, y) \leq d-t$; (ii) $B + I - \begin{bmatrix} v-t \\ d-t \end{bmatrix}^{-1} J$ is positive semidefinite and its i^{th} eigenvalue λ_i is positive precisely when $t+1 \leq i \leq d$, where we interpret $\begin{bmatrix} m \\ n \end{bmatrix}$ as $\binom{m}{n}$ for $J(v, d)$ and $\begin{bmatrix} m \\ n \end{bmatrix}_q$ for $J_q(v, d)$. We define \mathbf{f} by $f_0 = 1$, $f_1 = \dots = f_t = 0$, and $f_i = \begin{bmatrix} v-t \\ d-t \end{bmatrix}^{-1} \begin{bmatrix} v \\ d \end{bmatrix}^{-1} \lambda_i$ for $t+1 \leq i \leq d$. For $\Gamma = \text{Bil}_q(d, e)$ ($d \leq e$), Delsarte [7] constructed a *Singleton system*, i.e., a subset whose inner distribution $\mathbf{e}' = (e'_0, e'_1, \dots, e'_d)$ satisfies $e'_1 = \dots = e'_t = 0$ and $(\mathbf{e}'Q)_1 = \dots = (\mathbf{e}'Q)_{d-t} = 0$. It follows that e'_{t+1}, \dots, e'_d are positive; see [23, §4]. We define $\mathbf{f} = \mathbf{e}' \cdot \text{diag}(k_0, k_1, \dots, k_d)^{-1}$ where k_i is the valency of Γ_i ($0 \leq i \leq d$). For $\Gamma = H(d, q)$, a subset having the above properties is known as an MDS code [18, Chapter 11]. MDS codes may not exist for some d, q, t , but still \mathbf{e}' makes sense and is uniquely determined. If $t = d-1$ or $q \geq d$, or if $q = d-1$ and $t < d-2$, then it follows that e'_{t+1}, \dots, e'_d are positive; see e.g., [9, Appendix]. We again define $\mathbf{f} = \mathbf{e}' \cdot \text{diag}(k_0, k_1, \dots, k_d)^{-1}$.

Concerning the conclusion of Lemma 1, the classification of descendents has been done for the 15 known infinite families of Q -polynomial distance-regular graphs with so-called classical parameters and with unbounded diameter, including the above 4 families; see [4, 23, 24]. Moon [19] showed that the upper bound q^{d-t} for $H(d, q)$ and the characterization of its descendents as optimal intersecting families are valid under the (in general) weaker assumption $q \geq t+2$. Dual polar graphs discussed in [23] do not always possess \mathbf{f} even for the case $t = 1$ [22]; see [21], however, for a description of optimal 1-intersecting families.

3. THE ERDŐS-KO-RADO THEOREM FOR TWISTED GRASSMANN GRAPHS

Let q be a prime power and fix a hyperplane H of \mathbb{F}_q^{2d+1} . Let X_1 be the set of $(d+1)$ -dimensional subspaces of \mathbb{F}_q^{2d+1} not contained in H , and X_2 the set of $(d-1)$ -dimensional subspaces of H . The *twisted Grassmann graph* $\Gamma = \tilde{J}_q(2d+1, d)$ [5] has vertex set $X = X_1 \cup X_2$, and two vertices $x, y \in X$ are adjacent if $\dim x + \dim y - 2 \dim x \cap y = 2$. It has the same parameters (i.e., the structure constants of \mathbf{A}) as $J_q(2d+1, d)$. The twisted Grassmann graphs provide the first known family of non-vertex-transitive distance-regular graphs with unbounded diameter. See [12, 1, 20] for more information.

The Erdős-Ko-Rado theorem for $\tilde{J}_q(2d+1, d)$ can now be rapidly obtained. Note that $J_q(2d+1, d)$ and $\tilde{J}_q(2d+1, d)$ share the same Q . Hence we may use the vector \mathbf{f} for $J_q(2d+1, d)$ constructed in §2, and Lemma 1 applies. The descendents

²Leonard systems provide a linear algebraic framework characterizing the terminating branch of the Askey scheme [16] of (basic) hypergeometric orthogonal polynomials.

of $\tilde{J}_q(2d+1, d)$ have recently been classified by the author [24, Theorem 8.20]. To summarize:

Theorem 2. *Let Y be a nonempty subset of $\tilde{J}_q(2d+1, d)$ with width $w \leq d-t$, where $0 < t < d$. Then $|Y| \leq \begin{bmatrix} 2d+1-t \\ d-t \end{bmatrix}_q$, and equality holds if and only if $Y = \{x \in X_2 : u \subseteq x\}$ for some subspace u of H with $\dim u = t-1$. ■*

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